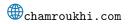
Statistical Learning

Master Spécialisé Intelligence Artificielle de Confiance (IAC) @ Centrale Supélec en partenariat avec l'IRT SystemX 2024/2025.

Faïcel Chamroukhi

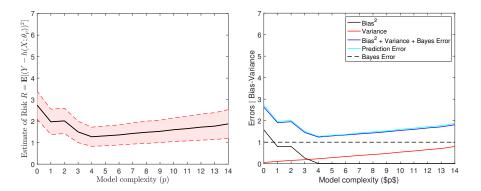






Risk Decomposition (Continued)

Bias-Variance Decomposition





Setting : Prediction under the squared loss

Prediction function

$$h \colon \mathbb{R}^p \to \mathbb{R}^d$$
$$x \mapsto h(x)$$

■ Squared (ℓ₂)-loss function :

$$\ell \colon \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}$$
$$(h(x), y) \mapsto \ell(y, h(x)) = (y - h(x))^2$$

Expected Risk

- Consider the Risk : $R_x(h) = \mathbb{E}_P[\ell(Y, h(X))|X = x] = \mathbb{E}_{Y|X=x}((Y - h(X))^2|X = x]$
- Best prediction function (Bayes predictor) : $h^*(x) = \mathbb{E}(Y|X = x)$.
- Bayes Risk : $R(h^*)$
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Bias-Variance Decomposition

$$\begin{split} \mathbb{E}[(h(X) - h^{*}(X))^{2}] &= \mathbb{E}[(h(X) - \mathbb{E}[h(X)] + \mathbb{E}[h(X)] - h^{*}(X))^{2}] \\ &= \mathbb{E}[(h(X) - \mathbb{E}[h(X)])^{2}] + \mathbb{E}[(\mathbb{E}[h(X)] - h^{*}(X))^{2}] \\ &+ 2 \underbrace{\mathbb{E}[(h(X) - \mathbb{E}[h(X)]) (\mathbb{E}[h(X)] - h^{*}(X))]}_{=0} \\ &= \underbrace{\mathbb{E}[(h(X) - \mathbb{E}[h(X)])^{2}]}_{\text{Variance}(h(X))} + \underbrace{\mathbb{E}[(\mathbb{E}[h(X)] - h^{*}(X))^{2}]}_{\text{Bias}^{2}(h(X), h^{*}(X))} \end{split}$$

- Bias : Systematic deviation of the average prediction from the true value.
- **Variance** : Amount of variability in the predictions for different training sets.
- **Bayes Error** : Intrinsic randomness in the target variable that no model can eliminate.



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The third term in the previous step vanishes because by conditioning on X and using the law of total expectations we get :

$$\mathbb{E}\big[(h(X) - \mathbb{E}[h(X)])(\mathbb{E}[h(X)] - h^*(X))\big] = \mathbb{E}\Big[\mathbb{E}[(h(X) - \mathbb{E}[h(X)])|X] \cdot (\mathbb{E}[h(X)] - h^*(X))\Big].$$

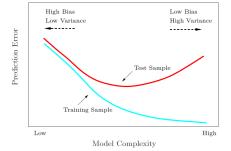
$$\mathbb{E}[h(X) - \mathbb{E}[h(X)]|X] = \mathbb{E}_{X}[\mathbb{E}[h(X) - \mathbb{E}[h(X)]|X]]$$

$$= \mathbb{E}[\mathbb{E}[h(X)|X] - \mathbb{E}[\mathbb{E}[h(X)]|X]]$$

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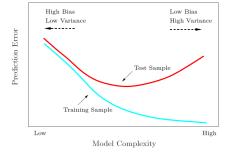
$$= \mathbb{E}[h(X)] - \mathbb{E}[h(X)]$$

$$= 0.$$



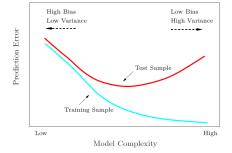


- If H has a large number of parameters, training a function h ∈ H can closely approximate h*, thereby reducing bias. However, it becomes sensitive to variations in the training set, leading to increased variance.
- If H has a small number of parameters, any function h ∈ H deviates from h*, increasing bias. However, it is less sensitive to fluctuations across different training sets, which results in lower variance.
- → increasing model complexity reduces squared bias but increases variance.
 Conversely, decreasing model complexity raises bias while reducing variance.
- → The goal is to find an optimal balance that minimizes the generalization error, which includes both bias and variance components.



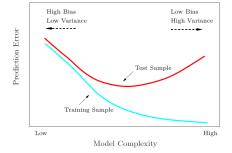


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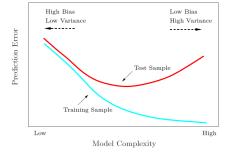


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- \blacksquare Consider the statistical model $Y=f(X)+\varepsilon,$ with f the true function
- ϵ_i 's are independent with $\mathbb{E}[\varepsilon|X] = 0$ and $\mathbb{E}[\varepsilon^2|X] = \sigma^2$
- Linear model : Consider $\mathcal{H} = \{h_{\theta}(x) = \alpha + \beta^T x\}$, the set of linear functions in x of the form $\theta^T \widetilde{x}$ with $\widetilde{x} = (1, x^T)^T$, and $\theta = (\alpha, \beta^T)^T$. (denote \widetilde{x} by x for simplicity)
- \blacksquare Bayes predictor h^* : for the squared loss : $h^*(x) = \mathbb{E}[Y|X=x] = f(x)$
- Let $\theta^* = (\alpha^*, \beta^{*T})^T$ be the optimal parameter. Then $h^*(x; \theta^*) = \theta^{*T}x = f(x)$ Assume a fixed design, i.e. the x's are deterministic
- Bayes Risk $R^* = R(h^*) = R(\theta^*) = \mathbb{E}[(Y h^*(X))^2 | X = x] = \mathbb{E}[\epsilon^2 | X = x] = \sigma^2$
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where $\widehat{\Sigma} = rac{1}{n} \sum_{i=1}^n x_i x_i^T$ and $\|u\|_A^2 = u^T A u.$

see proof in the next slide



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see proof in the next slide



Risk of any h (under the square loss) :

$$\begin{aligned} r(h(x)|X=x) &= \mathbb{E}_{Y|X}[\ell(Y,h(X))|X=x] = \mathbb{E}_{Y|X}[(Y-h(X))^2|X=x] \\ &= \mathbb{E}[(f(X)+\epsilon-h(X))^2] \\ &= \mathbb{E}[(f(x)-h(x))^2] + 2\mathbb{E}[\epsilon(f(x)-h(x))] + \mathbb{E}[\epsilon^2] \\ &= \underbrace{\mathbb{E}[(f(x)-h(x))^2]}_{\text{Bias-Variance}} + 2\underbrace{\mathbb{E}[\varepsilon]}_0 \mathbb{E}[(f(x)-h(x))] + \underbrace{\mathbb{E}[\epsilon^2]}_{\text{Irreducible Error}:\sigma^2} \\ &= \mathbb{E} \text{xcess Risk} + \text{Bayes Risk} \end{aligned}$$

. CHAMROUKHI Statistical Learning

(cont.)



Proof

$$R(\theta) = \mathbb{E}_{Y} \mathbb{E}_{X} [(Y - h(X))^{2} | x_{1}, \dots, x_{n}] = \mathbb{E}_{Y} \left[\frac{1}{n} \sum_{i=1}^{n} (Y_{i} - h_{\theta}(x_{i}))^{2} | x_{1}, \dots, x_{n} \right]$$

$$= \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{\varepsilon} [(x_{i}^{T}\theta + \varepsilon_{i} - x_{i}^{T}\theta^{*})^{2} | x_{i}]$$

$$= \frac{1}{n} \sum_{i=1}^{n} \left\{ \underbrace{\mathbb{E}_{\varepsilon} [\varepsilon_{i}^{2} | x_{i}]}_{\sigma^{2}} + (x_{i}^{T}(\theta - \theta^{*}))^{2} + 2 \underbrace{\mathbb{E}_{\varepsilon} [\varepsilon_{i} | x_{i}]}_{0} x_{i}^{T}(\theta - \theta^{*}) \right\}$$

$$= \underbrace{\sigma^{2}}_{R^{*}} + \underbrace{\frac{1}{n} \sum_{i=1}^{n} [x_{i}^{T}(\theta - \theta^{*})]^{2}}_{\text{Excess Risk}}$$

$$= R^{*} + \|\theta - \theta^{*}\|_{\widehat{\Sigma}}^{2} \text{ where } \widehat{\Sigma} = \frac{1}{n} \sum_{i=1}^{n} x_{i} x_{i}^{T} \text{ and } \|u\|_{A}^{2} = u^{T} A u.$$

(cont.)



Random θ (and fixed design) : $R(\theta) = R^* + Var(\theta) + (Bias(\theta, \theta^*))^2$

$$\begin{aligned} R(\theta) &= \mathbb{E}_{Y} \mathbb{E}_{X} [(Y - h(X))^{2} | x_{1}, \dots, x_{n}] = \mathbb{E}_{Y} \left[\frac{1}{n} \sum_{i=1}^{n} (Y_{i} - h_{\theta}(x_{i}))^{2} | x_{1}, \dots, x_{n} \right] \\ &= \frac{1}{n} \sum_{i=1}^{n} \left\{ \underbrace{\mathbb{E}_{\varepsilon} [\varepsilon_{i}^{2} | x_{i}]}_{\sigma^{2}} + \mathbb{E}_{Y} [(x_{i}^{T}(\theta - \theta^{*}))^{2}] + 2 \underbrace{\mathbb{E}_{\varepsilon} [\varepsilon_{i} | x_{i}]}_{0} \mathbb{E}_{Y} [x_{i}^{T}(\theta - \theta^{*})] \right\} \\ &= \underbrace{\sigma^{2}}_{R^{*}} + \underbrace{\mathbb{E}_{Y} [\frac{1}{n} \sum_{i=1}^{n} [x_{i}^{T}(\theta - \theta^{*})]^{2}]}_{\text{Excess Risk}} \\ &= R^{*} + \mathbb{E}_{Y} ||\theta - \theta^{*}||_{\widehat{\Sigma}}^{2} \\ &= R^{*} + \mathbb{E} ||\theta - \mathbb{E}[\theta] + \mathbb{E}[\theta] - \theta^{*}||_{\widehat{\Sigma}}^{2} \\ &= R^{*} + \mathbb{E} \left[||\theta - \mathbb{E}[\theta]||_{\widehat{\Sigma}}^{2} \right] + 2\mathbb{E} \left[(\theta - \mathbb{E}[\theta]) \widehat{\Sigma} (\mathbb{E}[\theta] - \theta^{*}) \right] + \mathbb{E} \left[||\mathbb{E}[\theta] - \theta^{*}||_{\widehat{\Sigma}}^{2} \right] \\ &= R^{*} + \operatorname{Var}(\theta) + 0 + (\operatorname{Bias}(\theta, \theta^{*}))^{2} \end{aligned}$$

MSE and Ordinary Least Squares (OLS)



• Empirical Risk : Under the squared loss the empirical risk $R_n(h)$ is

$$R_n(\theta) = \frac{1}{n} \sum_{i=1}^n \|y_i - h(x_i; \theta)\|_2^2 = \frac{1}{n} \sum_{i=1}^n \|y_i - \theta^T x_i\|_2^2$$
$$= \frac{1}{n} \|\mathbf{Y} - \mathbf{X}\theta\|_2^2 = \frac{1}{n} (\mathbf{Y} - \mathbf{X}\theta)^T (\mathbf{Y} - \mathbf{X}\theta)$$
with $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_n)^T$ and $\mathbf{Y} = (Y_1, \dots, Y_n)^T$

- ERM : $\hat{\theta}_n R_n(\theta) = \arg \min_{\theta \in \Theta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$ (whenever $\mathbf{X}^T \mathbf{X}$ is positive definite) is the Ordinary Least Squares Estimator of θ
- Calculation detail :

$$\nabla R_n(\widehat{\theta}) = \mathbf{0} \text{ (FOC)}$$

$$-2\mathbf{X}^T \mathbf{Y} + 2\mathbf{X}^T \mathbf{X} \widehat{\theta} = \mathbf{0}$$

$$\mathbf{X}^T \mathbf{X} \widehat{\theta} = \mathbf{X}^T \mathbf{Y} \text{ Normal equations}$$

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$$\widehat{\theta}_{\text{OLS}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y} \text{ whenever } \mathbf{X}^T \mathbf{X} \text{ is invertible}$$

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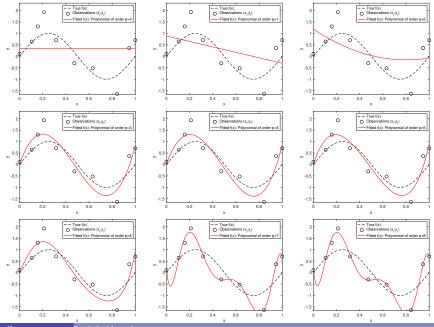
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Figure on Bias-Variance Tradeoff/Underfitting and Overfitting





JUKHI STA

Statistical Learning

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Setup to estimate the risk



Repeat :

- Fix an input x (or sample it from P(X) in cas of random design)
- Sample the (true) target y from the conditional distribution P(Y|x).

Repeat :

- Sample a training dataset $\mathcal{D}_n = \{(x_i, y_i)\}_{i=1}^n$ i.i.d. from P(x, Y).
- Run the learning algorithm on \mathcal{D}_n to obtain a predictor \hat{h}_n .
- Compute the prediction $\widehat{y} = \widehat{h}_n(x)$.
- Compute the loss $\ell(\widehat{y}, y)$.
- Average the losses.
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Notice : \hat{y} depends on \mathcal{D}_n , but y is sampled independently from \mathcal{D}_n .

Illustrations



Statistical learning of linear (polynomial) models

- True target function : $f(x) = 10 + 5x^2 \sin(2\pi x)$.
- The function is evaluated in the range $x \in [0, 1]$.

Observations are generated as :

$$Y_i | x_i \sim f(x_i) + \varepsilon_i, \quad i = 1, \dots, n.$$

- ▶ The dataset consists of *n* = 20 points.
- The x_i values are either fixed or randomly sampled in [0, 1].
- The noise ε_i follows a Gaussian distribution :

 $\varepsilon_i \sim \mathcal{N}(\mu_e, \sigma_e^2), \quad \text{where } \mu_e = 0, \quad \sigma_e = 1.$

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Illustrations



Statistical learning of linear (polynomial) models

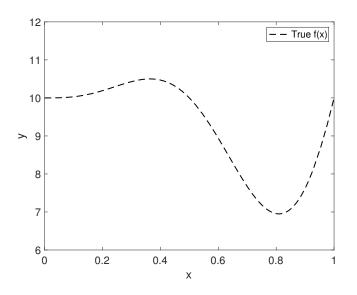
- True target function : $f(x) = 10 + 5x^2 \sin(2\pi x)$.
- The function is evaluated in the range $x \in [0, 1]$.
- Observations are generated as :

$$Y_i | x_i \sim f(x_i) + \varepsilon_i, \quad i = 1, \dots, n.$$

- The dataset consists of n = 20 points.
- The x_i values are either fixed or randomly sampled in [0, 1].
- The noise ε_i follows a Gaussian distribution :

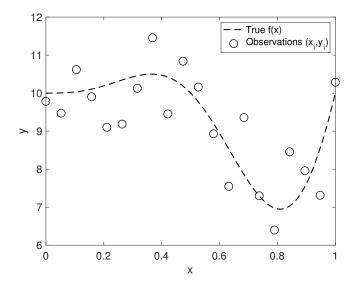
$$\varepsilon_i \sim \mathcal{N}(\mu_e, \sigma_e^2), \quad \text{where } \mu_e = 0, \quad \sigma_e = 1.$$

 $\blacksquare~N=100$ replicates (samples) for averaging



System×





Polynomial regression



Consider the class of polynomial models

$$\mathcal{H} = \{h_{\theta}(x) = \theta_0 + \theta_1 x + \theta_2 x^2 + \ldots + \theta_p x^p\}$$

the set of polynomials with \boldsymbol{p} the polynomial degree

- $\blacksquare \ p$ is ranging from 0 to 14
- ERM : $\widehat{\boldsymbol{\theta}}_n = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \boldsymbol{y}$ with

▶
$$\mathbf{X} = (x_1, \dots, x_n)^T$$
,
▶ $x_i = (1, x_i, x_i^2, \dots, x_i^p)^T$, and
▶ $y = (y_1, \dots, y_n)^T$

Polynomial regression



Consider the class of polynomial models

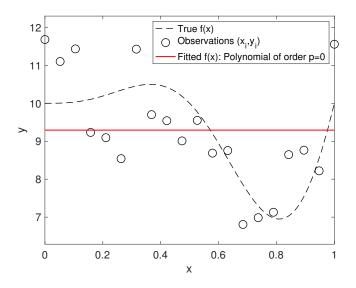
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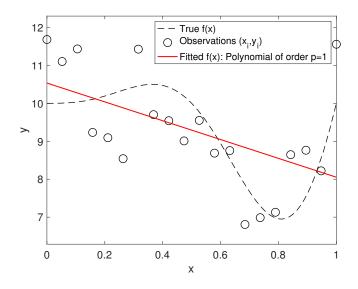
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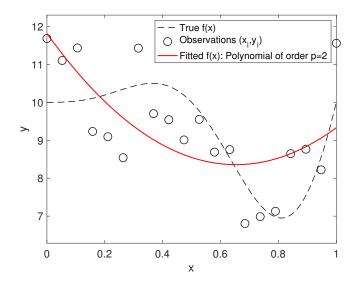




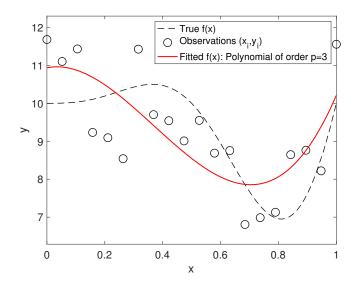




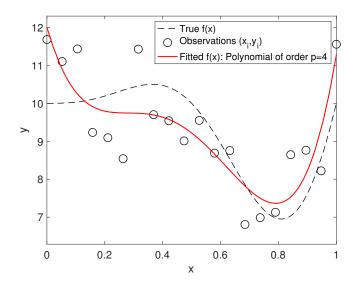




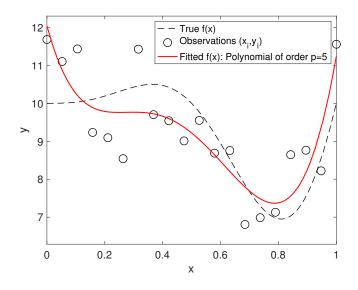




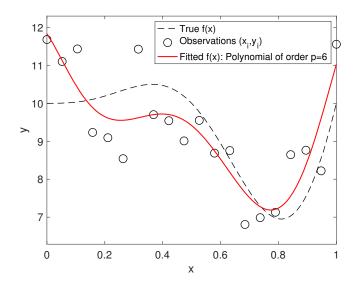




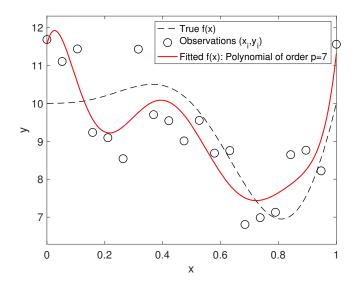




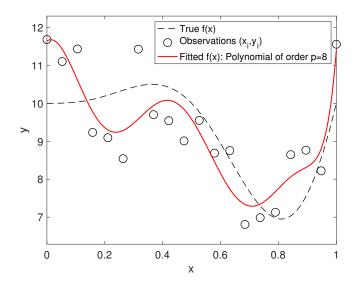




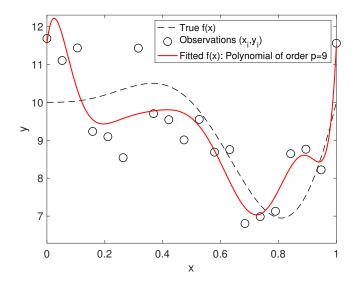




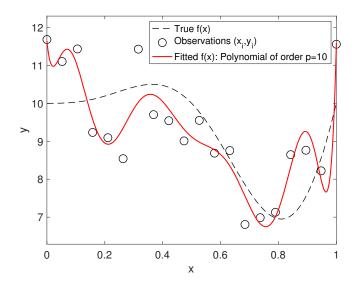




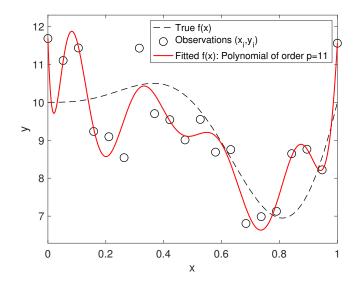




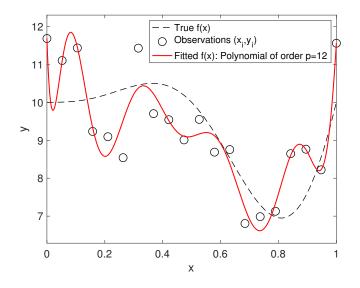




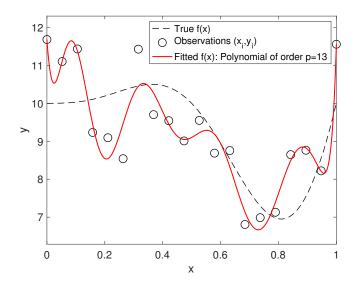




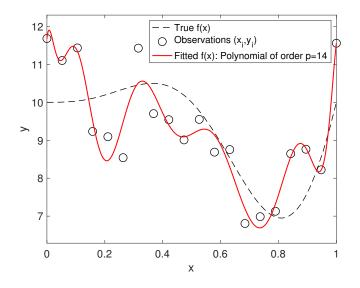




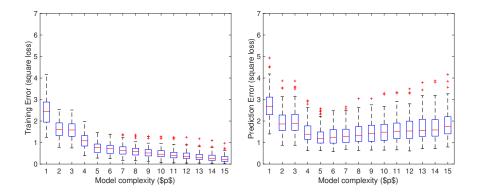


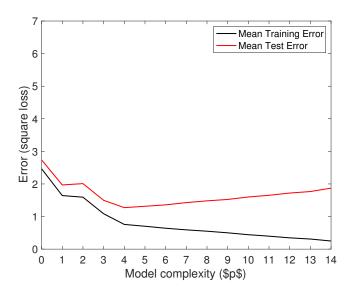




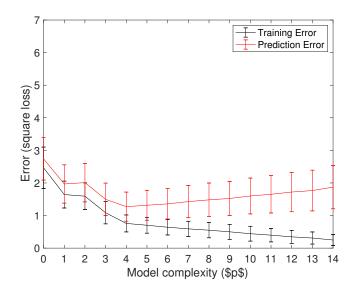








System×



System×

